



Interactive multi-objective evolutionary optimization of software architectures

Aurora Ramírez, José Raúl Romero, Sebastián Ventura

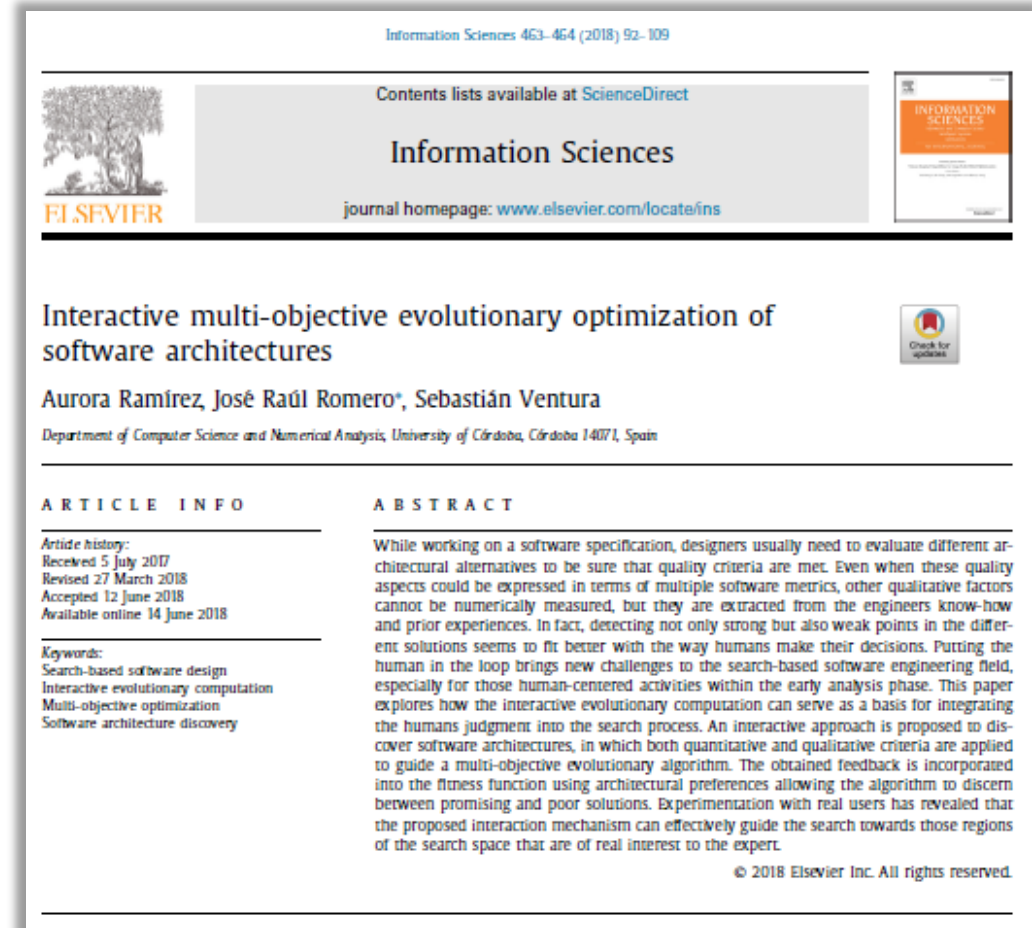
Dept. Computer Science and Numerical Analysis. University of Córdoba.

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A. Ramírez, J.R. Romero, S. Ventura. "Interactive multi-objective evolutionary optimization of software architectures". *Information Sciences*, vol. 463-464, pp. 92-109. 2018.



Introduction

- Software design is a **human-centered** task
- **Qualitative** aspects are difficult to quantify
- The engineer should be **involved** in the optimization process
- Sometimes it is easier to identify a **bad** solution rather than a **good** one



Introduction

RQ1: How can the qualitative judgement of the engineer be integrated into the evolutionary discovery of software architectures?

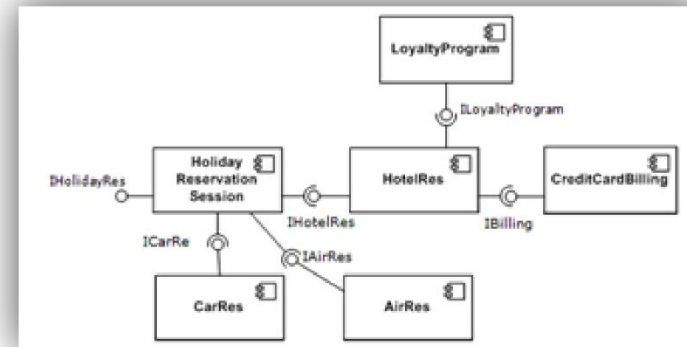
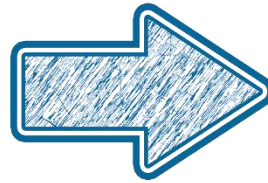
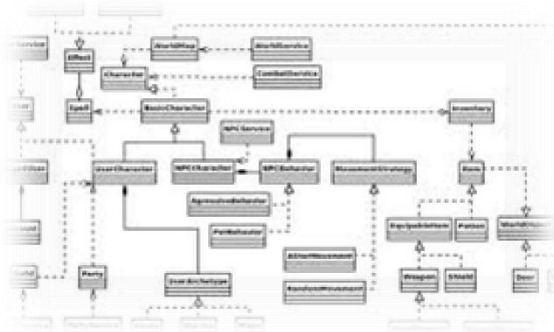
RQ2: Does putting the human in the loop involve a significant improvement compared with not considering him/her along the optimization process?



Background

Architecture discovery

To identify the underlying **component-based architecture** of the system from the analysis information contained in a UML class diagram



Component: a cohesive group of classes that work together to satisfy the expected behavior of the component

Interface: a directed relationship between classes belonging to different components

Connector: The linkage between required/provided interfaces

Background

Interactive optimization

Full automation is not always **realistic**:

- Uncertainty scenarios
- Creative tasks

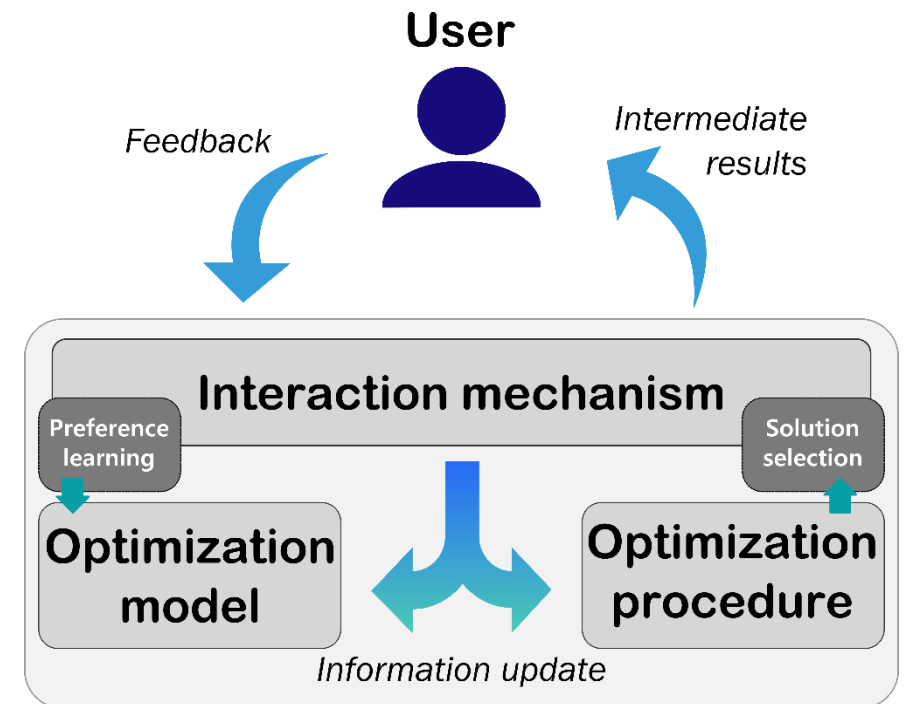
Human is “**put in the loop**”:

- To provide problem knowledge
- To increase trust on automatic results
- To meet user’s expectations

Design and implementation **decisions**:

- Selection of solutions
- Type of feedback
- Frequency of interaction
- Information lifetime

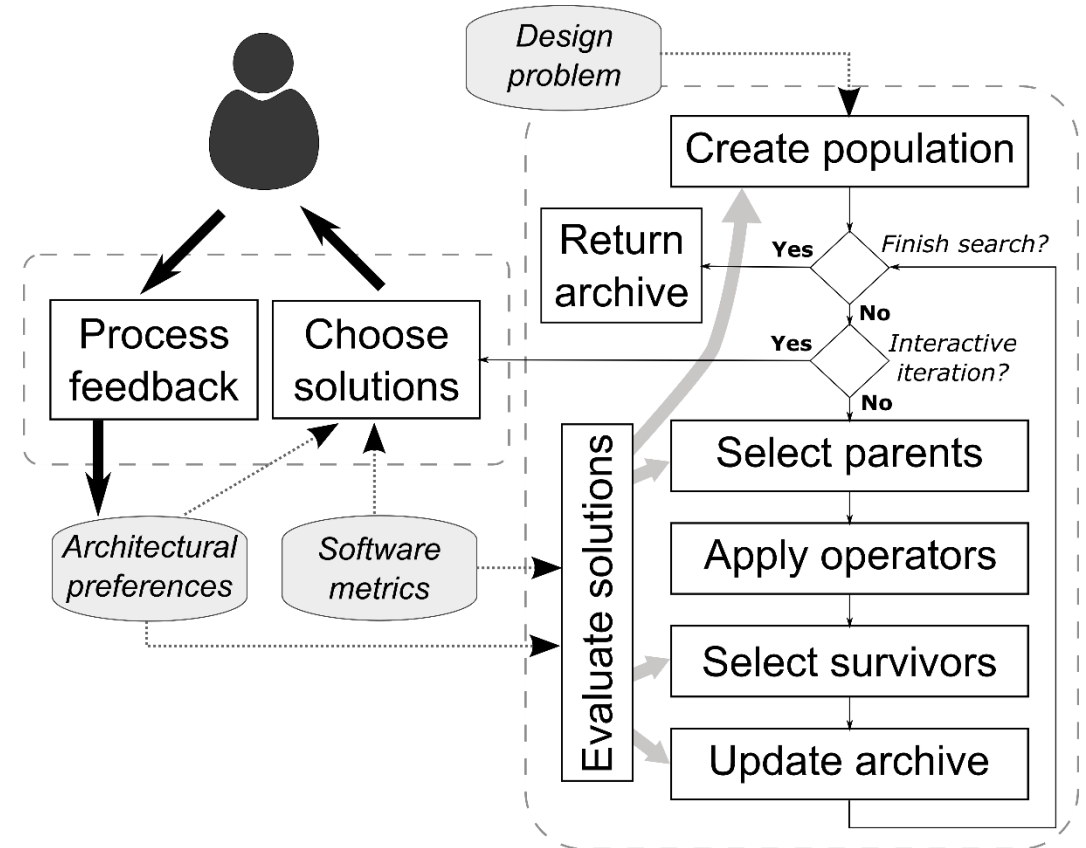
Any optimization method, including metaheuristics, in which the human **actively participates** in any step of the process to provide feedback



Interactive algorithm

Overview

- **Steady-state** algorithm: two offspring are produced in each generation
- **Archive** to store a small set of representative solutions
- Binary tournament selection from population and archive
- Offspring replace population members with worst fitness



Interactive algorithm

Fitness function

A novel **fitness function** that combines objective and subjective evaluation criteria

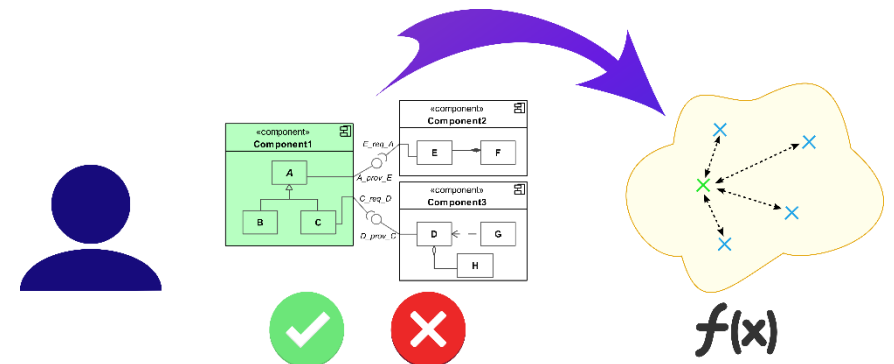
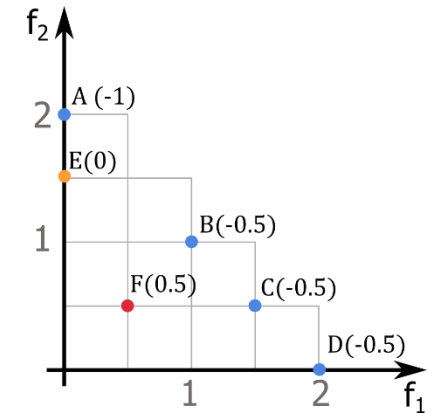
$$fitness(s) = w_{obj} \cdot f_{obj}(s) + w_{sub} \cdot f_{sub}(s)$$

Quantitative: Maximin function to quantify both dominance and diversity (software measures)

$$f_{obj}(s) = \frac{1 + \max_{z \neq s} (\min_k (f_k^s - f_k^z))}{2} \quad \forall z \in Z$$

Qualitative: Engineer's preferences on phenotypic aspects of the solution (architectural preferences)

$$f_{sub}(s) = 1 - \frac{1}{P} \cdot \sum_{p=1}^P w_p \cdot pref_p(s)$$



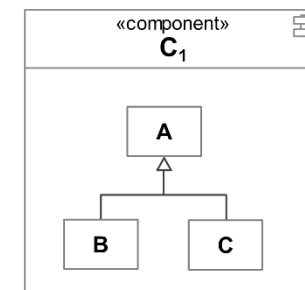
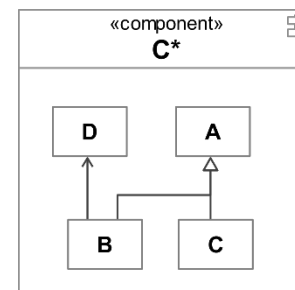
Interactive algorithm

Architectural preferences

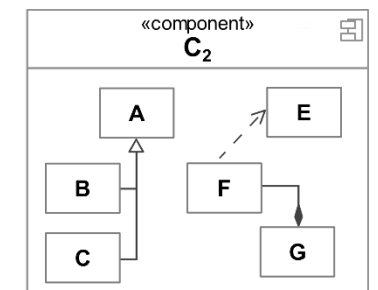
| Preference | Description |
|--------------------------|------------------------------------------|
| Best component | Similarity to the set of classes |
| Worst component | Dissimilarity to the set of classes |
| Best provided interface | Similarity to the set of operations |
| Worst provided interface | Dissimilarity to the set of operations |
| Number of components | Distance to the preferred number |
| Metric in range | Distance to the midrange |
| Aspiration levels | Weighted distance to the reference point |

$$pref_{bc}(s) = \max\{J(classes(c), classes(c^*))\} \quad \forall c \in [1, n]$$

$$J(A, B) = \frac{A \cap B}{A \cup B}$$



$$J(C^*, C_1) = 3/4 = 0.75$$

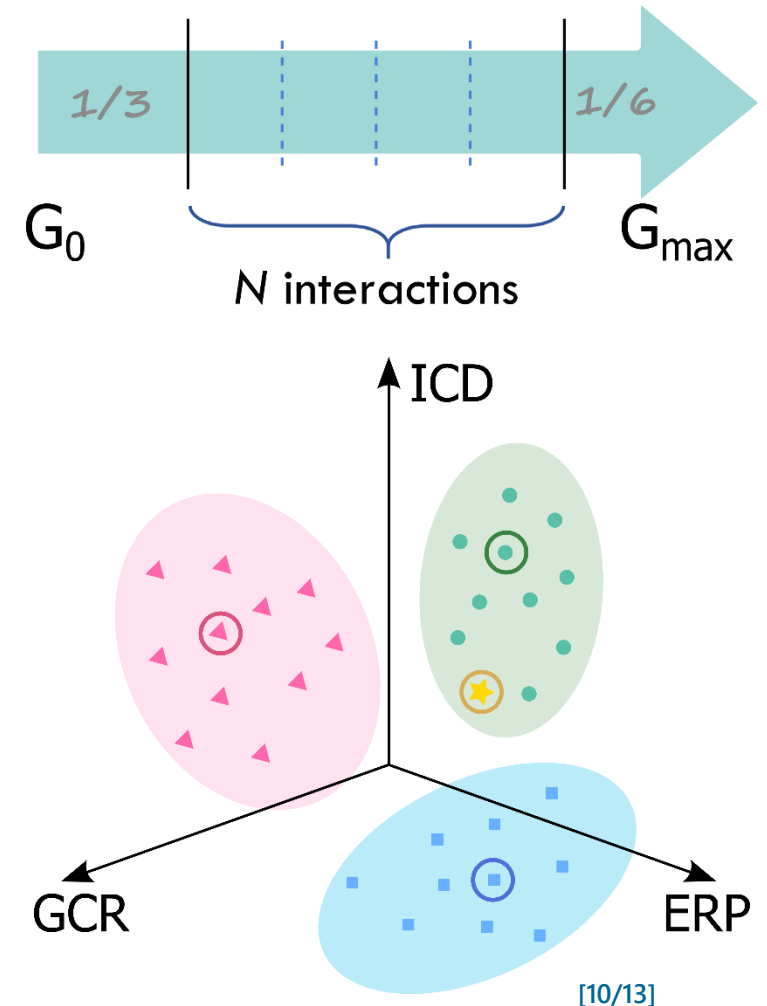


$$J(C^*, C_2) = 3/7 = 0.429$$

Interactive algorithm

Interaction mechanism

- Interactions are scheduled at **regular intervals**
- Solutions are selected from the current population using a **clustering** method
- The engineer **rewards or penalizes** some aspect of the solution by choosing one preference
- Additional **actions**:
 - Freeze one component
 - Add to the archive
 - Remove from the population
 - Stop the search



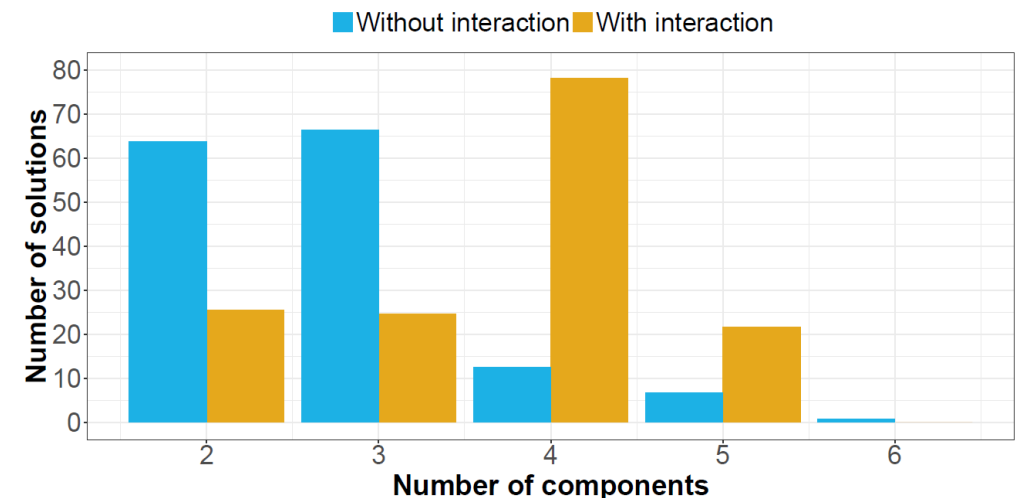
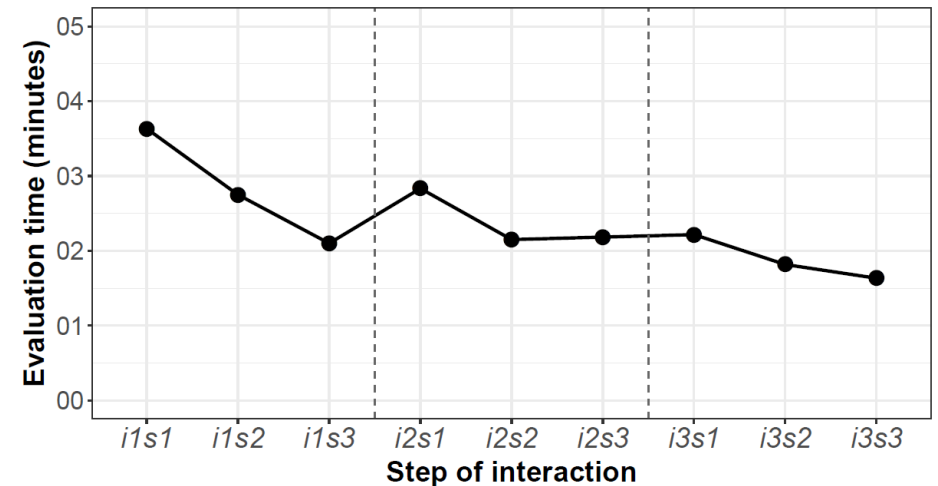
Empirical study

Methodology:

- Case study, 9 participants
- 3 interactions, 3 solutions each
- Log files and questionnaires

Impact of interaction:

- Cohesion is indirectly improved
- Different number of components
- Components are similar or equal to the manual design
- Actions (add, freeze) contribute to find better solutions

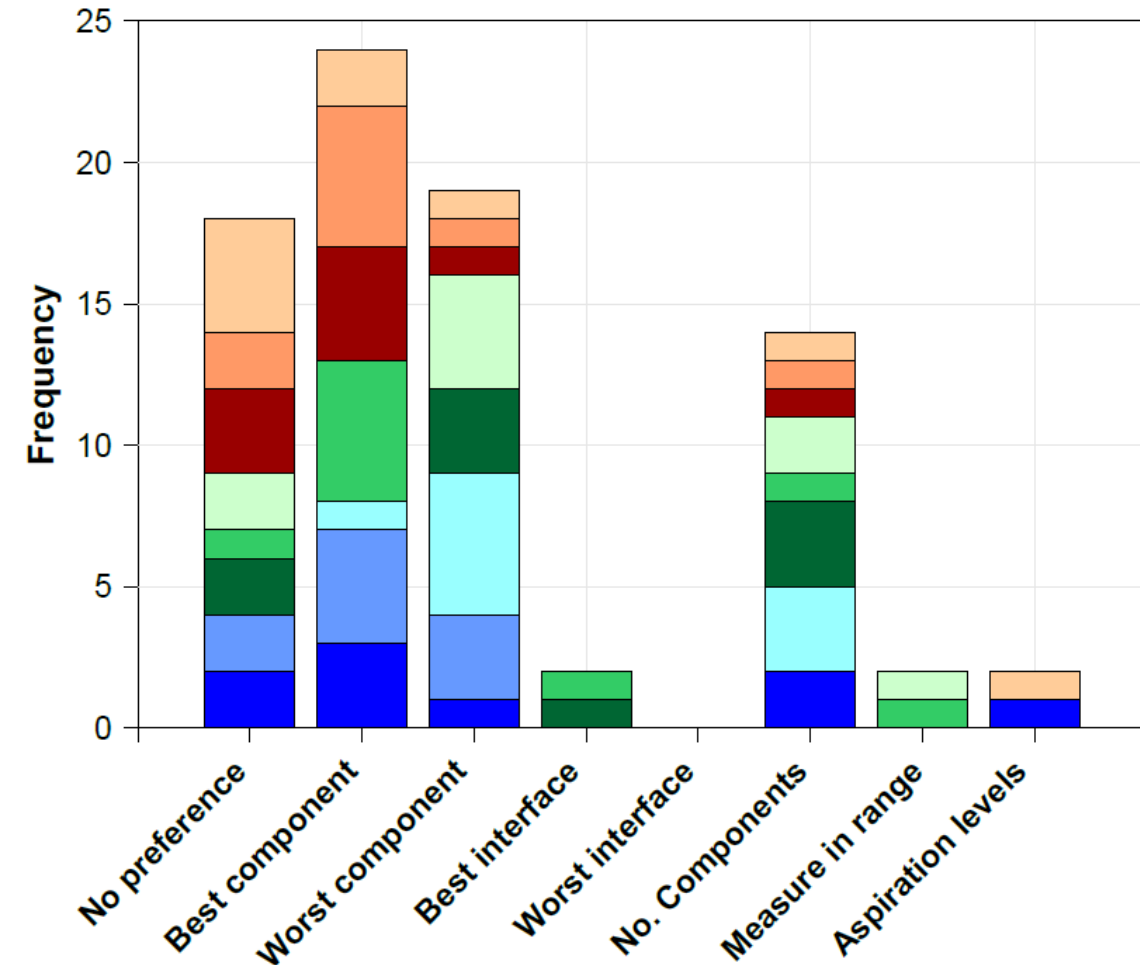


Empirical study

Analysis of architectural preferences:

- More interest in the internal structure
- Negative preferences are more frequently applied at the beginning
- Use of “no preference”

| Architectural preference | Selected (%) | Useful [1-8] | Intuitive [1-8] |
|--------------------------|--------------|--------------|-----------------|
| No preference | 22.22 | 6.44 | 7.33 |
| Best component | 29.63 | 7.44 | 7.44 |
| Worst component | 23.46 | 7.22 | 7.33 |
| Best prov. Interface | 2.47 | 5.29 | 6.38 |
| Worst prov. Interface | 0.00 | 4.71 | 6.38 |
| No. Components | 17.28 | 7.50 | 7.33 |
| Metric in range | 2.47 | 4.17 | 5.44 |
| Aspiration levels | 2.47 | 5.80 | 5.22 |



Conclusions

- ✓ Architectural preferences as a novel mechanism for subjective evaluation
- ✓ Design measures are still needed at the beginning
- ✓ Negative options are useful too
- ✓ Humans are willing to participate (even more) in the optimization

Future work:

- Improve the interactive experience (more preferences and flexibility)
- Analyze how other human design abilities could be integrated

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UNIVERSIDAD DE CORDOBA

Aurora Ramírez

 aramirez@uco.es

 <https://www.uco.es/users/aramirez>

 [@aurora_rq](https://twitter.com/aurora_rq)

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Interactive algorithm

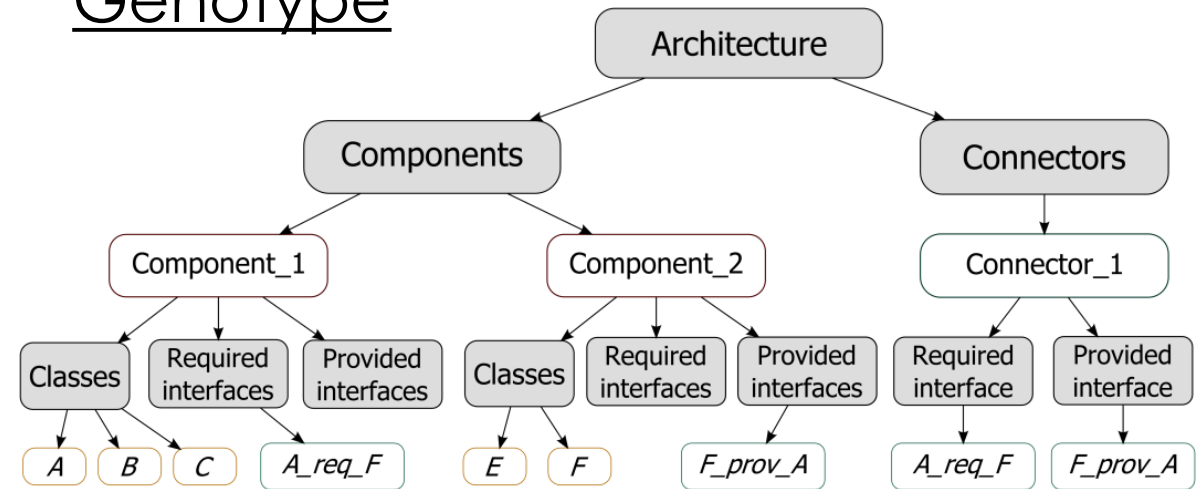
Problem representation and constraints

Architectural solutions
(individuals) are ***coded as multi-layered trees***

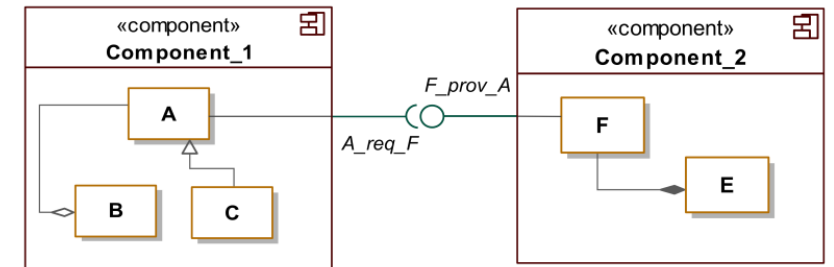
Initialization and constraints

1. Random distribution of classes
 - ✓ No empty components and no replicated classes
2. Set interfaces and connectors
 - ✗ Isolated or mutually dependant components

Genotype



Phenotype



Interactive algorithm

Architectural preferences

1) Best component

$$pref_{bc} = \max\{J(\text{classes}(c), \text{classes}(c^+))\} \forall c \in [1, n]$$

$$J(A, B) = |A \cap B| / |A \cup B|$$

2) Worst component

$$pref_{wc} = \max\{1 - J(\text{classes}(c), \text{classes}(c^-))\} \forall c \in [1, n]$$

3) Best provided interface

$$pref_{bi} = \max\{J(\text{operations}(\text{interface}(c)), \text{operations}(p^+))\} \forall c \in [1, n]$$

4) Worst provided interface

$$pref_{wi} = \max\{1 - J(\text{operations}(\text{interface}(c)), \text{operations}(p^-))\} \forall c \in [1, n]$$

5) Number of components

$$pref_{nc} = \begin{cases} (n - n_{min}) / (n^+ - n_{min}) & \text{if } n < n^+ \\ 1 - ((n - n^+) / (n_{max} - n)) & \text{if } n \geq n^+ \end{cases}$$

6) Metric in range

$$pref_{mr} = \begin{cases} 0 & \text{if } m^s < m_{min} \\ 1 - (m^s - m_{mid}) / m_{mid} & \text{if } m^s \in [m_{min}, m_{max}] \\ 0 & \text{if } m^s > m_{max} \end{cases}$$

$$m_{mid} = (m_{max} - m_{min}) / 2$$

7) Aspiration levels

$$pref_{al} = \begin{cases} 1 & \text{if } ASF \leq 0 \\ 1 - ASF & \text{if } ASF > 0 \end{cases}$$

$$ASF = \max\{w_k \cdot (f_k^s - z_k^*)\}$$